Performance of a link in a field of vehicular interferers with hardcore headway distance

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- Headway distance: Distance from the tip of a vehicle to the tip of its follower
- Location of vehicles is commonly modeled by a Poisson point process (PPP) in the literature
- In roads with few number of lanes the PPP assumption might not be accurate as it allows unrealistically small headways



Motivation

Complex headway models in transportation research

Balancing accuracy and tractability: Cowan M2 headway distance model has two components: A constant tracking distance + a random component following the exponential distribution [Cowan1975]



Intensity of vehicles

Distribution of inter-vehicle distances

$$\lambda = \frac{\mu}{1+\mu c}$$



System model

- Vehicles impenetrable disks of diameter c
- Transmitter-receiver link at the origin
- Fixed and known useful signal level P_r
- Vehicles outside of the guard zone $[-r_0, r_0]$ generate interference
- Distance-based pathloss $g(r) = r^{-\eta}, r > r_0$
- Exponential fading over interfering links h_k and over the transmitter-receiver link h_t
- Instantaneous interference level $\mathcal{I} = \sum_{k} h_k g(x_k)$



How does the deployment model for the vehicles (hardcore model vs a PPP of equal intensity λ) impact the performance of the transmitter-receiver link at the origin?

• Due to Campbell's theorem for stationary processes, the mean interference levels under the two models are equal

$$\mathbb{E}\{\mathcal{I}\} = 2\lambda \int_{r_0}^{\infty} x^{-\eta} \mathrm{d}x = \frac{2\lambda r_0^{1-\eta}}{\eta - 1}$$

- Interferers have correlated locations
 - Higher moments of interference and outage probability would be different under the two models
 - Cross-moments of interference would be different too and affect
 - Temporal performance, e.g., retransmission schemes
 - Spatial performance, e.g., multi-antenna receiver

Probability of outage

The calculation of the outage probability, $Pr_{out}(\theta) = \mathbb{P}(SIR \le \theta)$, requires the probability generating functional (PGFL) of the hardcore process generating the interference

$$\mathsf{Pr}_{\mathsf{out}}(\theta) = 1 - \mathbb{E}_{\mathsf{x}}\left\{\prod_{k} \frac{1}{1 + s \, x_{k}^{-\eta}}\right\}, \, s = \frac{\theta}{P_{r}}$$

A lower bound can be obtained by the PPP of equal intensity [Stucki2014]

$$\mathsf{Pr}_{\mathsf{out}}(\theta) \ge 1 - e^{-2\lambda \int_{r_0}^{\infty} \left(1 - \frac{1}{1 + sx^{-\eta}}\right) \mathrm{d}x}$$

An upper bound using the Jensen's inequality

$$\mathsf{Pr}_{\mathsf{out}}(\theta) \leq 1 - \exp\Bigl(-\mathbb{E}_{\mathsf{x}}\left\{\sum\nolimits_k \log\left(1 + \mathit{s} \mathit{x}_k^{-\eta}\right)\right\}\Bigr)$$

When the bounds become tight? - traffic conditions, system set-up, etc.

6 / 24

Available methods

- Factorial moment expansion for the PGFL [Westcott1972]
- Horizontal shift of the outage probability due to PPP [Guo2015]
- Converting distance distribution to aggregate interference level distribution
- Calculate few moments of interference distribution and select suitable probability function to approximate it
 - variance & ratio of standard deviation over the mean
 - skewness
 - temporal & spatial Pearson correlation coefficient of interference

The second moment of interference accepts contributions due to a single vehicle and also due to pairs

$$\mathbb{E}\left\{\mathcal{I}^{2}\right\} = \underbrace{\mathbb{E}\left\{h^{2}\right\} \int g^{2}(x) \lambda \mathrm{d}x}_{\frac{4\lambda r_{0}^{1-2\eta}}{2\eta-1}} + \mathbb{E}\left\{h\right\}^{2} \int g(x) g(y) \underbrace{\rho^{(2)}(x, y)}_{\frac{4\lambda r_{0}^{1-2\eta}}{2\eta-1}} \mathrm{d}x \mathrm{d}y$$

The calculation of the third moment of interference involves also triples of vehicles

Moment measures

Correlation properties for the hardcore model have been studied in the context of statistical mechanics [Salsburg1953]

• The pair correlation function (PCF) is

$$\rho^{(2)}(y,x) = \sum_{k=1}^{\infty} \rho_k^{(2)}(y,x), y > x.$$

$$\rho_k^{(2)}(y,x) = \begin{cases} \lambda \sum_{j=1}^k \frac{\mu^j (y-x-jc)^{j-1}}{\Gamma(j)e^{\mu(y-x-jc)}}, & y \in (x+kc, x+(k+1)c), k \ge 1\\ 0, & \text{otherwise.} \end{cases}$$

• Due to the 1D nature of the deployment, higher-order intensity measures are also available

$$\rho^{(3)}(x, y, z) = \frac{1}{\lambda} \rho^{(2)}(x, y) \rho^{(2)}(y, z), \, x < y < z.$$

For small λc , the PCF of the hardcore process converges quickly (few multiples of the hardcore distance c) to the PCF λ^2 of a PPP of equal intensity



We will use the exact PCF only for small distances, e.g., up to 2c, and the PCF due to a PPP of equal intensity beyond that distance – This approximation does not introduce much error for small λc



11 / 24

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Approximation for the variance

Starting from

$$\mathbb{E}\left\{\mathcal{I}^{2}\right\} = \underbrace{\mathbb{E}\left\{h^{2}\right\} \int g^{2}(x) \lambda \mathrm{d}x}_{\frac{4\lambda r_{0}^{1-2\eta}}{2\eta-1}} + \mathbb{E}\left\{h\right\}^{2} \int g(x) g(y) \underbrace{\rho^{(2)}(x, y)}_{\frac{4\lambda r_{0}^{1-2\eta}}{2\eta-1}} \mathrm{d}x \mathrm{d}y$$

After substituting the approximation for the PCF, $\mu = \frac{\lambda}{1-\lambda c}$, and expanding around $\lambda c \rightarrow 0 \& \frac{c}{r_0} \rightarrow 0$, the variance of interference becomes

$$\mathbb{V}\{\mathcal{I}\}\approx\underbrace{\frac{4\lambda r_{0}^{1-2\eta}}{2\eta-1}}_{\text{PPP}(\lambda)}\left(1-\lambda c+\frac{1}{2}\lambda^{2}c^{2}\right),$$

Remark 1

Since the mean interference levels under the two models are equal, the distribution of interference for small λc becomes more concentrated around the mean as compared to that due to a PPP of intensity λ .

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Vehicular interference model

Approximation for the skewness

Approximating the third-order intensity measure $\rho^{(3)}(x, y, z)$ similar to the PCF, and expanding the third-moment for $\lambda c \rightarrow 0$ & $\frac{c}{m} \rightarrow 0$ we get

$$\mathbb{S}\{\mathcal{I}\} \approx \underbrace{\frac{12\lambda r_0^{1-3\eta}}{3\eta - 1} \left(\frac{4\lambda r_0^{1-2\eta}}{2\eta - 1}\right)^{-\frac{3}{2}}}_{\mathsf{PPP}(\lambda)} \left(1 - \frac{\lambda c}{2}\right)$$

Remark 2

For small λc , the distribution of interference becomes more symmetric between the tails and remains positively-skewed as compared to that due to a PPP of intensity λ .

Remark 3

For fixed λc , the variance and the skewness of interference are proportional to $\frac{1}{\sqrt{\lambda r_0}}$. The error of PPP increases for smaller cell size and lower intensity of vehicles.

Selecting the interference model

- Due to the guard zone, the pathloss model is bounded, and the tails of interference strongly depend on the fading process [Pappas2015]
- **2** Skewness is positive for small λc

The Gamma and shifted-gamma probability distribution function (PDF) along with Rayleigh fading meet the above criteria For fixed $\lambda c = 0.4$, a lower intensity λ is associated with higher skewness, and three moments clearly provide better fit than two.



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Probability of outage

Both models have simple Laplace transforms

• gamma PDF

$$f_{\mathcal{I}}(x) \approx \frac{x^{k-1}e^{-x/\beta}}{\Gamma(k)\beta^k}, \ \operatorname{Pr}_{\operatorname{out}}(\theta) \approx 1 - (1+s\beta)^{-k},$$

where
$$k = \frac{\mathbb{E}\{\mathcal{I}\}^2}{\mathbb{V}\{\mathcal{I}\}}$$
 and $\beta = \frac{1}{k}$.

shifted-gamma PDF

$$f_{\mathcal{I}}(x) \approx \frac{(x-\epsilon)^{k-1} e^{-(x-\epsilon)/\beta}}{\Gamma(k) \beta^{k}}, x \ge \epsilon, \operatorname{Pr}_{\operatorname{out}}(\theta) \approx 1 - e^{-s\epsilon} (1+s\beta)^{-k},$$

where
$$k = \frac{4}{\mathbb{S}\{\mathcal{I}\}^2}, \beta = \sqrt{\frac{\mathbb{V}\{\mathcal{I}\}}{k}}$$
 and $\epsilon = \mathbb{E}\{\mathcal{I}\} - k\beta$.

Numerical illustrations - Probability of outage

For fixed $\lambda c = 0.4$, the PPP starts to fail in the upper tail for microcells and also in macrocells with sparse flows The two models (gamma, shifted-gamma) fit very well the simulations

Microcell $r_0 = 100 \text{ m}$

Macrocell $r_0 = 250 \text{ m}$





Mean delay

- We use static and independent realizations of interferers over the time slots to model low and high mobility respectively along microcells
- For independent realizations of interferers over time, the mean delay is the inverse of the probability of successful reception $\mathbb{E}\{D\} = \frac{1}{1 \Pr(\theta)}$
- For static interferers over time

$$\mathbb{E}\{D\} \approx \sum_{t=0}^{\infty} \sum_{T=t}^{\infty} (-1)^t \binom{T}{t} (1+s\beta(t))^{-k(t)} \\ = \lim_{T_0 \to \infty} \sum_{t=0}^{T_0} (-1)^t \binom{T_0+1}{t+1} (1+s\beta(t))^{-k(t)}$$

where
$$k(t) = \frac{\mathbb{E}\{\mathcal{I}(t)\}^2}{\mathbb{V}\{\mathcal{I}(t)\}}, \ \beta(t) = \frac{1}{k(t)}.$$

$$\mathbb{E}\{\mathcal{I}(t)\} = \frac{2\lambda r_0^{1-\eta} t}{\eta - 1}, \mathbb{V}\{\mathcal{I}(t)\} \approx \frac{2\lambda r_0^{1-2\eta} t \left(1 + t(1 - \lambda c)^2\right)}{2\eta - 1}.$$

Numerical illustrations – Mean delay

For static interferers, the two models are characterized by different temporal correlation of interference

- The temporal correlation coefficient of interference for the PPP is $\frac{1}{2}$
- For small λc , the correlation coefficient for the hardcore model is approximately equal to $\frac{1}{2}(1 \lambda c)$



Instantaneous interference at the two antennas

$$\mathcal{I}_{1} = \sum_{i} h_{1,i} g\left(x_{i}\right), \ \mathcal{I}_{2} = \sum_{i} h_{2,i} g\left(x_{i}\right)$$

Sum the post combining SIR conditioned on the interference vector

$$\mathbb{P}\{\mathsf{SIR} \ge \theta\} = \mathbb{E}_{\mathsf{I}}\left\{\mathbb{P}\left(\frac{h_{t,1}P_r}{\mathcal{I}_1} + \frac{h_{t,2}P_r}{\mathcal{I}_2} \ge \theta|\mathsf{I}\right)\right\}$$

Condition on the SIR for the second branch w [Tanbourgi2014]

$$\mathbb{P}\{\mathsf{SIR} \geq \theta\} = \mathbb{E}_{\mathsf{I},W}\left\{e^{-s_1\mathcal{I}_1}\right\} = \mathbb{E}_{\mathsf{I}}\left\{\int_0^\infty e^{-s_1(w)\mathcal{I}_1} f_{W|\mathcal{I}_2}(w) \,\mathrm{d}w\right\},\$$

where
$$s_1(w) = \frac{\max\{0, \theta - w\}}{P_r}$$

For Rayleigh fading, the conditional PDF is $f_{W|\mathcal{I}_2}(w) = \frac{\mathcal{I}_2}{P_r} e^{-s_2(w)\mathcal{I}_2}$, where $s_2(w) = \frac{w}{P_r}$

$$\begin{split} \mathbb{P}\{\mathsf{SIR} \geq \theta\} &= \frac{1}{P_r} \int_0^\infty \mathbb{E}_{\mathsf{I}} \{\mathcal{I}_2 e^{-s_1 \mathcal{I}_1} e^{-s_2 \mathcal{I}_2} \} \, \mathrm{d}w \\ &= \frac{1}{P_r} \int_0^\theta \mathbb{E}_{\mathsf{I}} \{\mathcal{I}_2 e^{-s_1 \mathcal{I}_1} e^{-s_2 \mathcal{I}_2} \} \, \mathrm{d}w + \frac{1}{P_r} \int_\theta^\infty \mathbb{E}_{\mathsf{I}} \{\mathcal{I}_2 e^{-s_2 \mathcal{I}_2} \} \, \mathrm{d}w, \end{split}$$

Using the differentiation property of Laplace transform

$$\mathbb{P}\{\mathsf{SIR} \ge \theta\} = P_r^k \left(P_r + \theta\beta\right)^{-k} + k\beta P_r^{2k} \int_0^\theta \frac{1 + \beta \left(\theta - w\right) \left(1 - \rho\right) \,\mathrm{d}w}{\left(P_r^2 + \theta\beta P_r + \left(\theta - w\right) w\beta^2 \left(1 - \rho\right)\right)^{k+1}}$$

Dual-branch MRC

- The outage probability prediction using the PPP model worsens with two antennas at receiver
- The outage probability due to a PPP is not anymore a bound (lower tail) – overall limited use



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- The hardcore distance makes the interference distribution more concentrated around the mean and less skewed
- The PPP of equal intensity gives a lower bound for the outage probability with single-antenna receiver
 - The PPP bound fails when the coefficient of variation and the skewness of interference are high
 - Associated traffic scenarios are urban microcells & macrocells with sparse flow of vehicles
- The performance prediction of PPP worsens with temporal performance metrics and multi-antenna receivers because the hardcore distance impacts the correlation properties of interference too

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24 / 24